

GNSS SIGNALS INTRODUCTION

Gabriella Povero Navigation Technologies GNSS Training AIT, Bangkok 14 -18 January 2019

GNSS IN ONE SLIDE

A **Global Navigation Satellite System** (GNSS) consists of a constellation of satellites with global coverage, whose payloads are especially designed to provide **positioning of objects**



GNSSs implement the trilateration method (spherical positioning systems)

The satellites are at known positions, as we know satellite **orbits** and **time**.

Satellite broadcast signals toward users on Earth

All the information data necessary to perform the trilateration are contained in the **Signal in Space** (SIS) transmitted by the satellites



THE NAVIGATION EQUATION





THE NAVIGATION SOLUTION

If we consider 4 satellites:

measured

$$\begin{cases}
\rho_{1} = \sqrt{(x_{s1} - x_{0})^{2} + (y_{s1} - y_{0})^{2} + (z_{s1} - z_{0})^{2}} + b_{r} \\
\rho_{2} = \sqrt{(x_{s2} - x_{0})^{2} + (y_{s2} - y_{0})^{2} + (z_{s2} - z_{0})^{2}} + b_{r} \\
\rho_{3} = \sqrt{(x_{s3} - x_{0})^{2} + (y_{s3} - y_{0})^{2} + (z_{s3} - z_{0})^{2}} + b_{r} \\
\rho_{4} = \sqrt{(x_{s4} - x_{0})^{2} + (y_{s4} - y_{0})^{2} + (z_{s4} - z_{0})^{2}} + b_{r} \\
\end{cases}$$
measured
Known
(written in the navigation message)

$$\begin{array}{c}
x_{0}, y_{0}, z_{0}, b_{u} \\
4 \text{ unknowns} \\
b_{r} = c \cdot b_{u}
\end{array}$$



THE NAVIGATION EQUATION

REMARKS

- In order to estimate its position a receiver must have at least four satellites in view
- The satellites must be in Line-of-Sight
- If a larger number of satellites is in view a better estimation is possible. In the past the combination of four satellites giving the best performance was chosen
- Modern receivers use **several channels** in order to perform the position estimation







MULTI-GNSS





The signals broadcast by the navigation satellites:

- Allow the user to estimate the distance (pseudorange) user-satellite
- Carry some useful data
- Be robust to the transmission through the atmosphere
- Identify in a unique way the satellites

The SIS is characterised by:

- Frequency Band
- Carrier Frequency
- Modulation Scheme
- Multiplexing Format
- Ranging Code
- Navigation Data Format
- Transmitted Power

$$x_{RF}(t) = \sqrt{2P_c}c(t)d(t)\cos(2\pi f_L t + \theta_{L1})$$



Note: in the graphs the signal periods are not realistic (only pictorial)





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GNSS SIS - FREQUENCIES AND BANDS







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GNSS SIS - MODULATION SCHEMES

- In legacy navigation SISs, the used modulation schemes are:
 - BPSK
 - QPSK
- In new and modernized SISs, innovative modulation schemes have been proposed (BOC, MBOC, ...)

BPSK is the simplest form of phase shift keying (PSK).

It uses two phases which are separated by 180°. Low data rate (1 bit/symbol)

Best BER performance among PSK modulations

QPSK can be obtained as the combination of 2 BPSK signals: one in-phase and the other in quadrature (90° phase shift) Data rate: 2 bits/symbol









SPLIT SPECTRUM MODULATION

- One way to reduce mutual interference between signals modulated over the same carrier is to **introduce a frequency shift**, modulating one of the signals with a subcarrier
- In the navigation field this technique has been named
 Binary Offset Carrier (BOC) modulation
- Split spectrum:

the energy is allocated around BOC subcarrier frequency and not at the central frequency





GNSS SIS - CDMA

- Code Division Multiple Access (CDMA) is a multiple-access technique for transmitters sharing the same band
- The data-signal band is multiplied by a code, which is unique for each transmitter





The code signal is a binary sequence, generally referred to as <u>pseudo noise</u> (*PN*)



GNSS SIS – CDMA AND SPREAD SPECTRUM

Data signal with a narrow band B_x is combined with a PN code (wider band)

The bandwidth B_y of the resulting signal is the sum of band B_x and the large band of the code (Fourier transform property)





GNSS SIS – CDMA AND SPREAD SPECTRUM

Data signal with a narrow band B_x is combined with a PN code (wider band)

- The total transmitted power does not change
- The bandwidth B_y of the resulting signal is larger than B_x. The name "spread spectrum" indicates that the spectrum is spread
- The level of the power spectral density decreases





























GNSS SIS - FDMA



Frequency domain

Time domain



GALILEO SIS

- One of the major driver in the Galileo signal design has been the interoperability with GPS
- Interoperability means that receivers have to be potentially able to deal with both the systems, thus with both the Signals-In-Space
- As a consequence, SIS must be in close bandwidths, without interfering each-other
- The open access service (free and unencrypted) signal share the same carrier of GPS C/A code (L1)
- BOC modulation introduced to reduce inter-system interference







GALILEO BASELINE SIGNAL AND FREQUENCY PLAN



GALILEO BASELINE SIGNAL AND FREQUENCY PLAN





GALILEO BASELINE SIGNAL AND FREQUENCY PLAN

Signal	Carrier Frequency (MHz)	Receiver Reference Bandwidth (MHz)		
E1	1575.420	24.552		
E6	1278.750	40.920		
E5	1191.795	51.150		
E5a	1176.450	20.460		
E5b	1207.140	20.460		
Data channel Code ————————————————————————————————————	Modulation Modulation Data	X-band signal		
Data channel Code Pilot channel Code (present or not) Code	Modulation Modulation			

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C

Carrier Frequency (MHz)

1575.420

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- 2 Navigation Signals (3 channels) transmitted in E1 band:
 - **E1** (E1-B, E1-C): open access signals with navigation data
 - E1P: restricted access signal (PRS)
- Coherent Adaptive Sub-Carrier Modulation (CASM) multiplexing

Signal	Channels	Modulation	Rc (Mcps)	Rd (sps)	Power level (dBW)	Services	Multipl ex. scheme
E1-B Data		CBOC(6,1,1/11)	1.023	250	Min: -157	OS ,CS	
E1	E1-C Pilot	CBOC(6,1,1/11)	1.023		Max: - 154/-150	(I/NAV)	CASM
E1P	E1-A Data	BOC _{cos} (15,2.5)	2.5575	N/A	N/A	PRS	

E1 MULTIPLEXING TECHNIQUE

• CASM : Coherent Adaptative Subcarrier Modulation

$$\widetilde{S}_{E1}(t) = \frac{\sqrt{2}}{3} \left[e_{E1-B}(t) - e_{E1-C}(t) \right] + j \frac{1}{3} \left[2e_{E1-P}(t) + e_{E1,\text{int}}(t) \right]$$

INTERMODULATION PRODUCT TO ASSURE CONSTANT ENVELOPE

• Relative power levels:

Channels	Before multiplexing	After multiplexing
E1-B data	25%	22%
E1-C pilot	25%	22%
E1-P	50%	44%
IM		11%



Carrier Frequency (MHz)

1278.750

2 Navigation Signals (3 channels):

- E6 (E6-B data and E6-C pilot channels): commercial access signal
- > **E6P** (data channel): restricted access signal (PRS)

Signal	Channels	Modulation	Rc (Mcps)	Rd (sps)	Power level (dBW)	Services	Multiplex. scheme
ГС	E6-B Data	BPSK(5)	5.115	1000	Min: -155	CS	
Eb	E6-C Pilot	BPSK(5)	5.115		Max: -152	(C/NAV)	CASM
E6P	Data	BOC _{cos} (10,5)	5.115		Min: -155 Max: -152	PRS	



GALILEO E5 SIGNALS

2 Navigation Signals (4 channels):

- E5a: open access signal containing basic data for navigation and timing
- E5b: open access signal containing navigation and integrity data



Carrier Frequency

AltBOC multiplexing

Signal	Channels	Modulatio n	Rc (Mcps)	Rd (sps)	Power level (dBW)	Services	Multiplex. scheme
EEa	E5a-l Data	BPSK-like	10.23	50	Min:-155	OS (F/NAV)	AltBOC(15,10)
EDd	E5a-Q Pilot	BPSK-like	10.23		Max: -152		
FFb	E5b-l Data	BPSK-like	10.23	250	Min:-155	OS/CS (I/NAV)	
EDD	E5b-Q Pilot	BPSK-like	10.23		Max: -152		

ALTBOC MODULATION

- AltBOC Modulation allows the use of E5 band in two separate sidebands (E5a and E5b)
- In each sideband: 2 I-Q BPSK = 1 QPSK signal
 - Galileo receivers can use one or both sidebands
 - Multiple codes locally generated and correlated (challenging implementation of RX)
- AltBOC is equivalent to 8-PSK

From the receiver point of view:

BPSK Signals

- One or both sidebands separately
- Received in non-coherent mode
- Triangular correlation
- GPS receivers like

AltBOC architecture

- Entire bandwidth
- Coherently received
- Narrower correlation
- More complex structure



GALILEO SPREADING CODE LENGTHS

- Spreading codes are used to acquire and track a specific satellite. Each channel and satellite has a different code (CDMA)
- Galileo signals features depend on their code properties
- Code carefully selected by considering:
 - length
 - relation to data rates
 - auto/cross-correlation properties of the codes
- Code lengths:
 - Data channels: code period duration is equal to one symbol duration.
 - Pilot channels: long pilot code periods (100 ms) to improve cross-correlation and channel isolation, as well as noise and interference suppression.
 - **Tiered code construction:** short primary and long secondary codes used to build the code





GALILEO SPREADING CODE LENGTHS

Channel	Code rate (Mcps)	Data Rate (symbol/s)	Code period (ms)	Code length (chips)
E5a-I data	10.230	50	20	204600
E5a-Q pilot	10.230	Pilot	100	1023000
E5b-I data	10.230	250	4	40920
E5b-Q pilot	10.230	Pilot	100	1023000
E6-B data	5.115	1000	1	5115
E6-C pilot	5.115	Pilot	100	1023000
E1-B data	1.023	250	4	4092
E1-C pilot	1.023	Pilot	100	1023000

These information are valid for signals excluded PRS service





GALILEO NAVIGATION MESSAGE

- Galileo Message Data Stream : The navigation message is transmitted in the data stream as a sequence of frames.
- Each frame consists of a certain number (depending on the signal band) of subframes which contain several pages.







A three levels error coding is applied to the GALILEO Message Data Stream:

- A Cyclic Redundancy Check (CRC) with error <u>detection</u> <u>capabilities</u> after recovery of the received data
- A one-half rate Forward Error Correction (FEC). Tail Bits (sequence of zeros) to allow Viterbi decoding.
- Block Interleaving on the resulting frames: provides robustness to the FEC decoding algorithm by avoiding packets of errors

FEC and CRC are defined according to BER and FER targets.





GALILEO REFERENCE DOCUMENTS

https://www.gsc-europa.eu/electronic-library/





EUROPEAN GASSIGALLEOI IN THAL SERVICES OPEN SERVICE SERVICE DEFINITION DOCUMENT





EUROPEAN GNSS (GAULED) OPEN SERVICE SIGNAL-IN-SPACE INTERFACE CONTROL DOCUMENT



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CONTACT

GABRIELLA POVERO

gabriella.povero@linksfoundation.com www.navsas.eu www.ismb.it

LINKS FOUNDATION

Via Pier Carlo Boggio 61 | 10138 Torino

+(039) 011 2276 150



@linksfoundation

@linksfoundation



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linksfoundation.com